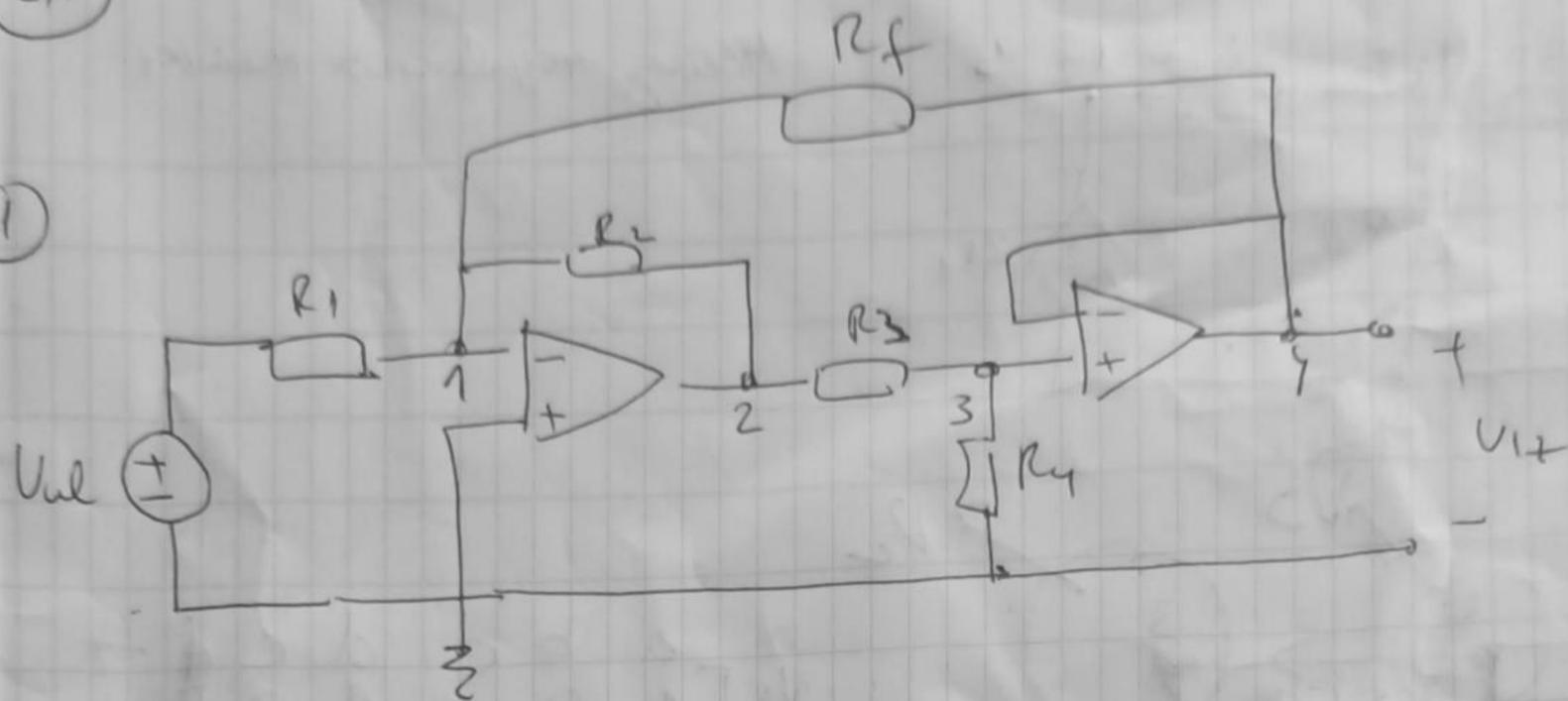


(G1)

(1)



$$V_1 = 0$$

$$\left( \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_f} \right) V_1 - \frac{1}{R_2} V_2 - \frac{1}{R_f} V_4 = \frac{U_{ul}}{R_1} \quad (1)$$

$$V_3 = V_4$$

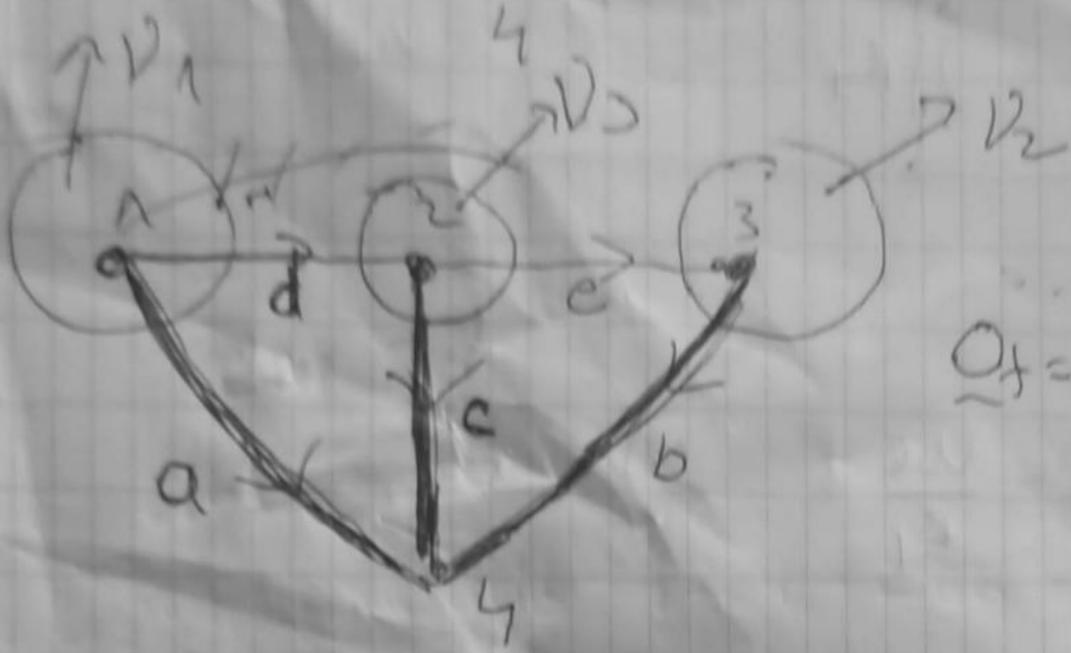
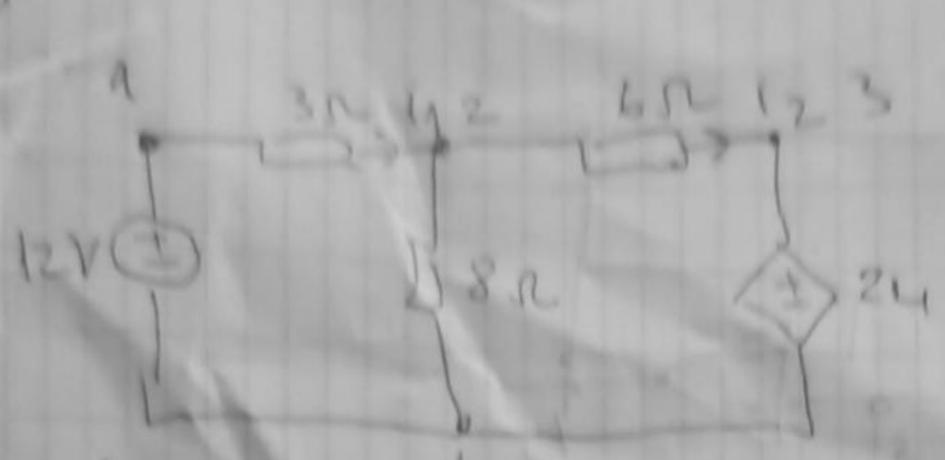
$$\left( \frac{1}{R_3} + \frac{1}{R_4} \right) V_3 - \frac{1}{R_3} V_2 = 0 \Rightarrow \frac{1}{R_3} V_2 = \left( \frac{1}{R_3} + \frac{1}{R_4} \right) V_4 \Rightarrow V_2 = \left( 1 + \frac{R_3}{R_4} \right) V_4 \quad (2)$$

$$(2) \rightarrow (1) \Rightarrow -\frac{1}{R_2} \left( 1 + \frac{R_3}{R_4} \right) V_4 - \frac{1}{R_f} V_4 = \frac{U_{ul}}{R_1}$$

$$\left( -\frac{1}{R_2} \left( 1 + \frac{R_3}{R_4} \right) - \frac{1}{R_f} \right) V_4 = \frac{U_{ul}}{R_1}, \quad V_4 = U_{12}$$

$$\Rightarrow \frac{U_{12}}{U_{ul}} = - \frac{1}{\frac{R_1}{R_2} + \frac{R_1 R_3}{R_2 R_4} + \frac{R_1}{R_f}}$$

2)



$$Q_f = \begin{bmatrix} v_1 & a & b & c & d & e \\ v_2 & 1 & 0 & 0 & 1 & 0 \\ v_3 & 0 & 1 & 0 & 0 & -1 \\ & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$$

$$U = Q_f^T \cdot U_T$$

$$\begin{bmatrix} U_a \\ U_b \\ U_c \\ U_d \\ U_e \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & -1 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} U_a \\ U_b \\ U_c \end{bmatrix}$$

$$\begin{aligned} U_d &= U_a - U_c \\ U_e &= -U_b + U_c \end{aligned}$$

$$\begin{aligned} U_a &= 12 \text{ V} \\ U_b &= 24 = 2U_d \end{aligned}$$

$$\Rightarrow U_d = 12 - U_c$$

$$U_e = -2U_d + U_c \Rightarrow U_e = -2(12 - U_c) + U_c = -24 + 3U_c$$

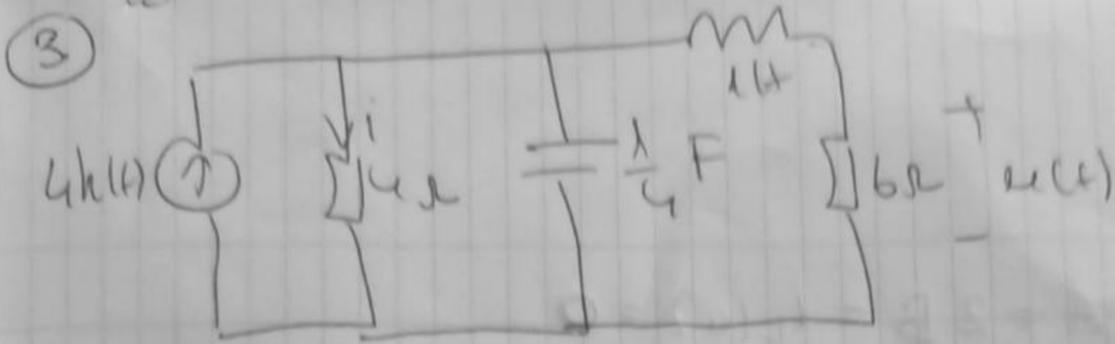
$$I_d = I_e + I_c \Rightarrow \frac{U_d}{3} = \frac{U_e}{6} + \frac{U_c}{8}$$

$$\Rightarrow 4 - \frac{U_c}{3} = -\frac{24}{6} + \frac{U_c}{2} + \frac{U_c}{8}$$

$$8 = \frac{U_c}{3} + \frac{U_c}{2} + \frac{U_c}{8} \Rightarrow U_c = 8.34$$

$$U_d = 3.66 \Rightarrow I_1 = 1.22 \text{ A}$$

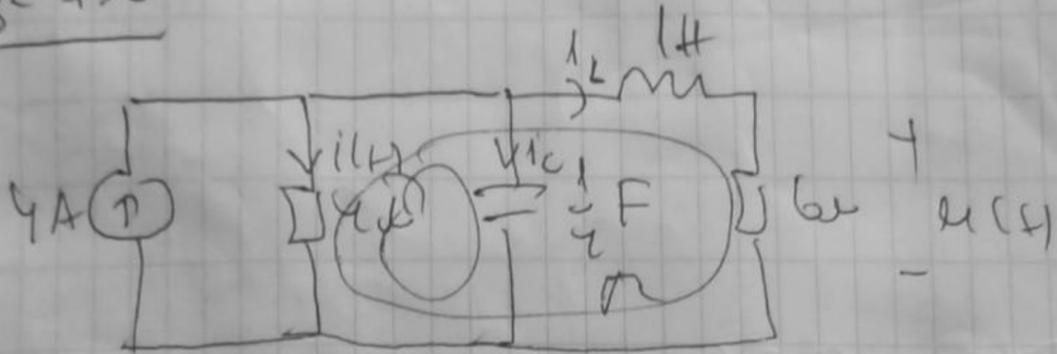
$$U_e = -24 + 3U_c = 1.02 \text{ V} \Rightarrow I_2 = 0.17 \text{ A}$$



se  $t < 0$

$$i_L(0^-) = 0 \text{ A} \quad u_C(0^-) = 0 \text{ V}$$

se  $t > 0$



$$i(t) = ?$$

$$4 = i + i_C + i_L \quad (1)$$

$$u_C = 4i \Rightarrow i_C = C \frac{du_C}{dt} = 4C \frac{di}{dt} = \frac{di}{dt}$$

$$4 \cdot i = u_L + 6 \cdot i_L \Rightarrow 4i = L \frac{di_L}{dt} + 6 \cdot i_L \quad (2)$$

$$\Rightarrow (1) \Rightarrow i_L = 4 - i - i_C$$

$$\rightarrow (2) \Rightarrow 4 \cdot i = L \frac{d(4 - i - \frac{di}{dt})}{dt} + 6 \cdot (4 - i - \frac{di}{dt})$$

$$(D^2 + 7D + 10)i = 24 \quad (3)$$

$$s^2 + 7s + 10 = 0$$

$$s_{1,2} = \frac{-7 \pm \sqrt{49 - 40}}{2} \Rightarrow s_1 = -5, \quad s_2 = -2$$

$$\Rightarrow i_h(t) = A e^{-5t} + B e^{-2t}$$

$$i_p = k \quad (4) \rightarrow 10k = 24 \Rightarrow k = 2.4$$

$$i = A e^{-5t} + B e^{-2t} + 2.4$$

$$u_C(t) = 4i(t) \Rightarrow u_C(0^+) = 4A + 4B + 9.6 = u_C(0^-) = 0$$

$$4(A+B) = -9.6 \Rightarrow A+B = -2.4 \Rightarrow A = -2.4 - B \quad (5)$$

$$L = 4 - 1 - \frac{di}{dt}$$

$$L(0^+) = 4 - A - B - 2 \cdot 4 + 5A + 2B = L(0^-) = 0$$

$$-1.6 = 4A + B$$

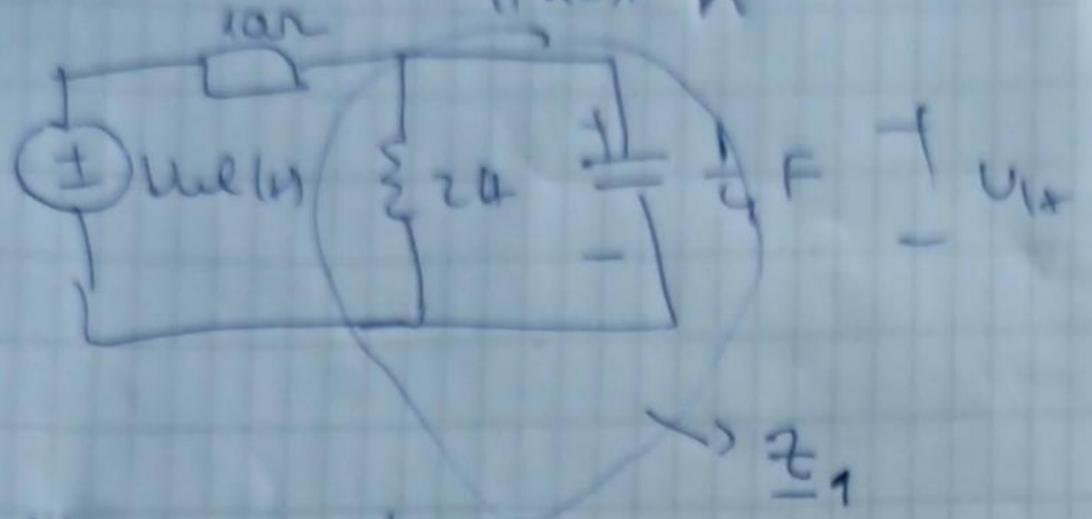
$$A = 0.26 \quad B = -2.66$$

$$i(t) = 0.26e^{-5t} - 2.66e^{-2t} + 2.4, \quad t > 0$$

4.

$$u_{in}(t) = 3 + \frac{4}{\pi} \sum_{k=1}^{\infty} \frac{1}{k} \sin(k\pi t)$$

$\omega = \pi$



$$Z_1^{(k)} = \frac{j k \omega L \cdot \frac{1}{j k \omega C}}{j k \omega L + \frac{1}{j k \omega C}} = \frac{j k \omega L}{1 - k^2 \omega^2 L C}$$

$$u_{1+}^{(k)} = \frac{Z_1^{(k)}}{Z_1^{(k)} + R} u_{in}^{(k)} \Rightarrow u_{1+}^{(k)} = \frac{j k \omega L}{j k \omega L + 10 - 10 k^2 \omega^2 L C} u_{in}^{(k)}$$

$$\Rightarrow u_{1+}^{(k)} = \frac{j k \omega L}{j k \omega L + 10 - 10 k^2 \omega^2 L C} \quad u_{in}^{(k)} = \frac{2 j k \omega}{2 j k \omega + 10 - 5 k^2 \omega^2} u_{in}$$

$u_{1+}^{(k)} = 0V$

za AC:  $= \frac{2 j k \omega}{2 j k \omega + 10 - 5 k^2 \omega^2} \cdot \frac{4}{k \omega}$

$u_{1+}^{(k)} = \frac{8}{\sqrt{(10 - 5k^2 \omega^2)^2 + 4k^2 \omega^2}} \cdot A_k \cdot \sin(k\pi t + \varphi_k)$

$= \frac{8j}{2 j k \omega + 10 - 5 k^2 \omega^2}$

$u_{1+}(t) = \sum_{k=1}^{\infty} A_k \sin(k\pi t + \varphi_k)$

$P_A = \left(\frac{4}{\pi \sqrt{2}}\right)^2 W$